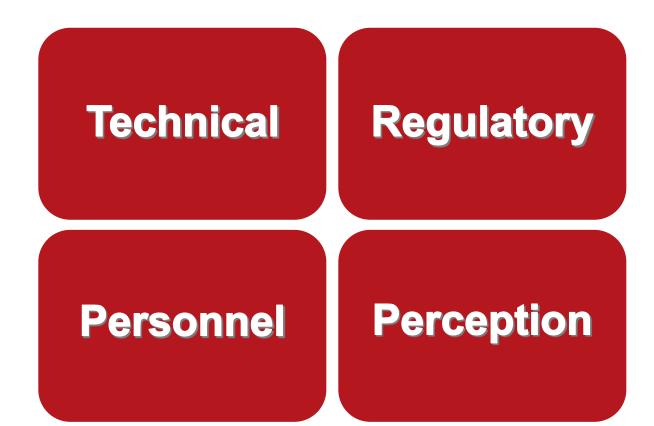


CHALLENGES OF AI-DRIVEN VEHICLES

Mike McNair, Bell

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What is Autonomy?

Autonomy Levels for Unmanned Systems (ALFUS)

Environmental Complexity

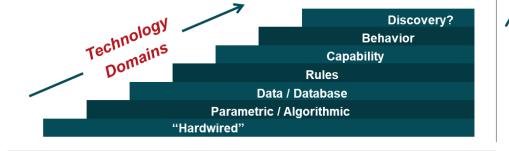
Solution ratios on: -Terrain variation -Object frequency, density, intent -Climate -Mobility constraints -Communication dependencies

Mission Complexity -Subtasks, decision -Organization, collaboration -Performance

-Performance -Situation awareness, knowledge requirements

Human Independence

-Frequency, duration, robot initiated interactions -Workload, skill levels -Operator to UMS ratio

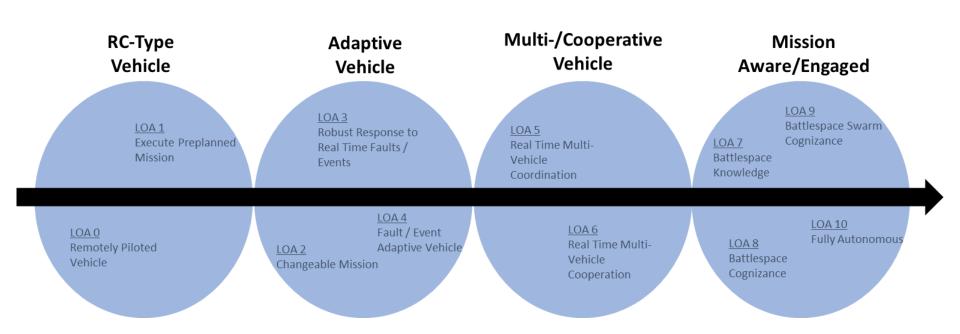




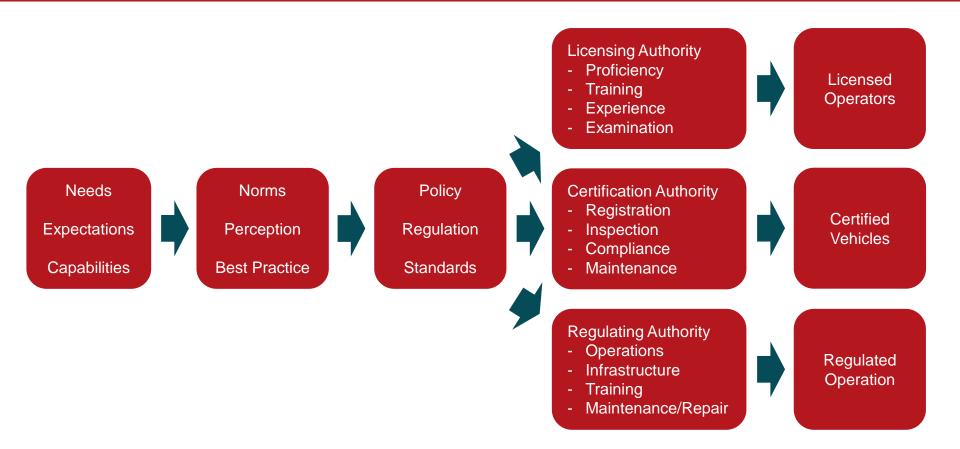
Autonomy Measures

4

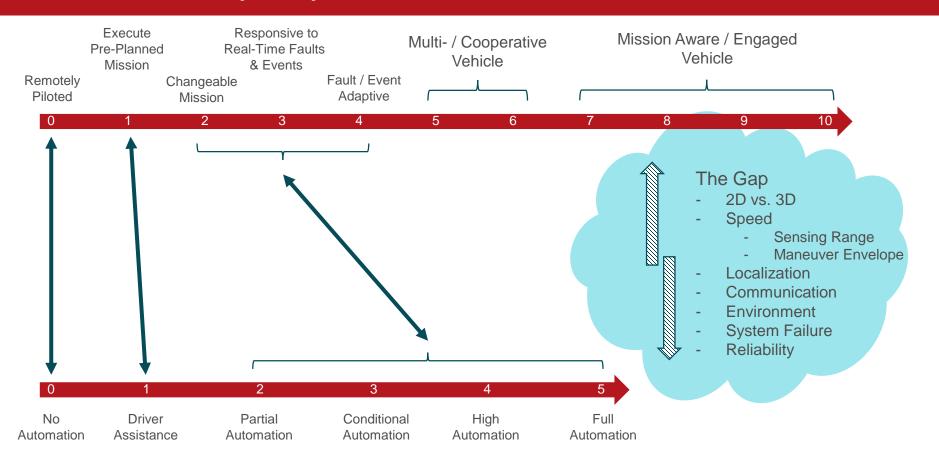
Autonomy and Al



Generic (and simplified) Licensing and Certification Flow

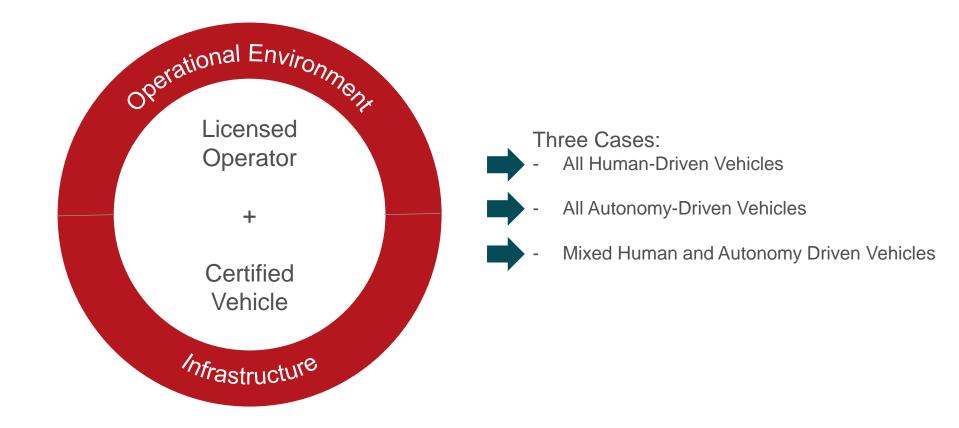


Controls & Autonomy – Key Differences Between Air and Ground



7

Complexities of a Heterogeneous Control Environment



Unique Gaps to Bridge

Our current state ...

- We treat machines differently than we treat people
- Machines have no stake in any outcome
- Non-deterministic without accountability is uncomfortable

What we strive for ...

- Reliability
- Explainability
- Perception and Intent
- Forensics

- De-Mystify and Generalize Artificial Intelligence
- Continue to mature sensing and decision-making approaches
- Re-examine certification and licensing requirements
- Re-think human and machine roles in existing and new use cases

THANK YOU